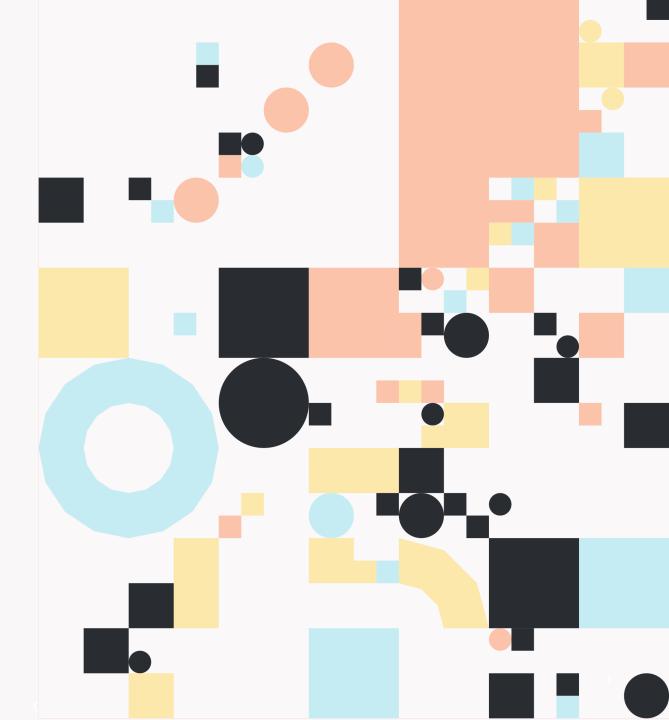
# GRAPHCORE WORKSHOP FOR TAMU

## October 3, 2023

Alexander Tsyplikhin

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### AGENDA

- Introduction to Graphcore, IPU, and Poplar
  - Hands-on: access the POD, enable the SDK, run an example
- TensorFlow2/Keras
  - Hands-on: Port a Keras script, leverage loop on device, replicate and run data-parallel, pipeline
- PyTorch
  - Hands-on: PopTorch example, DataLoader, options to optimize performance



# **GRAPHCORE ENABLING MACHINE INTELLIGENCE**



- Founded in 2016
- Technology: Intelligence Processor Unit (IPU)
- Team: ~500
- Offices: UK, US, China, Poland
- Raised >\$710M

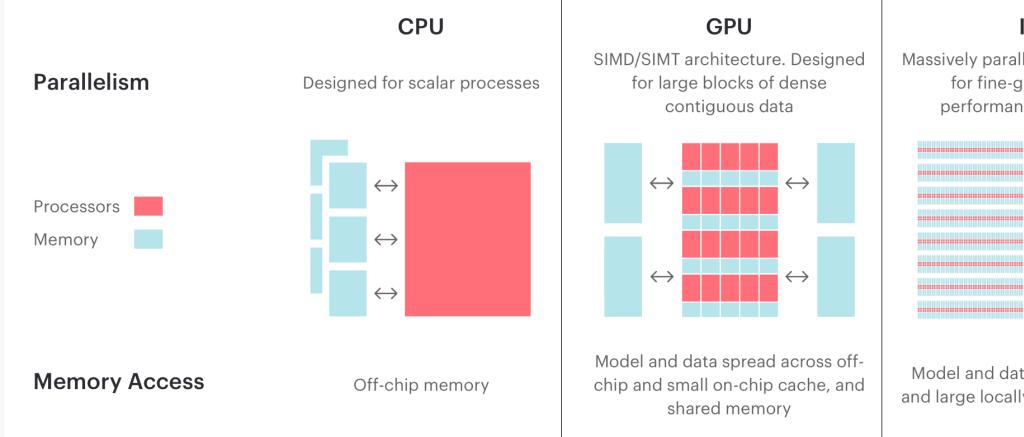


### GRAPHCORE IPU LETS INNOVATORS CREATE THE NEXT BREAKTHROUGHS IN MACHINE INTELLIGENCE



## **IPU – ARCHITECTURED FOR AI**

Massive parallelism with ultrafast memory access



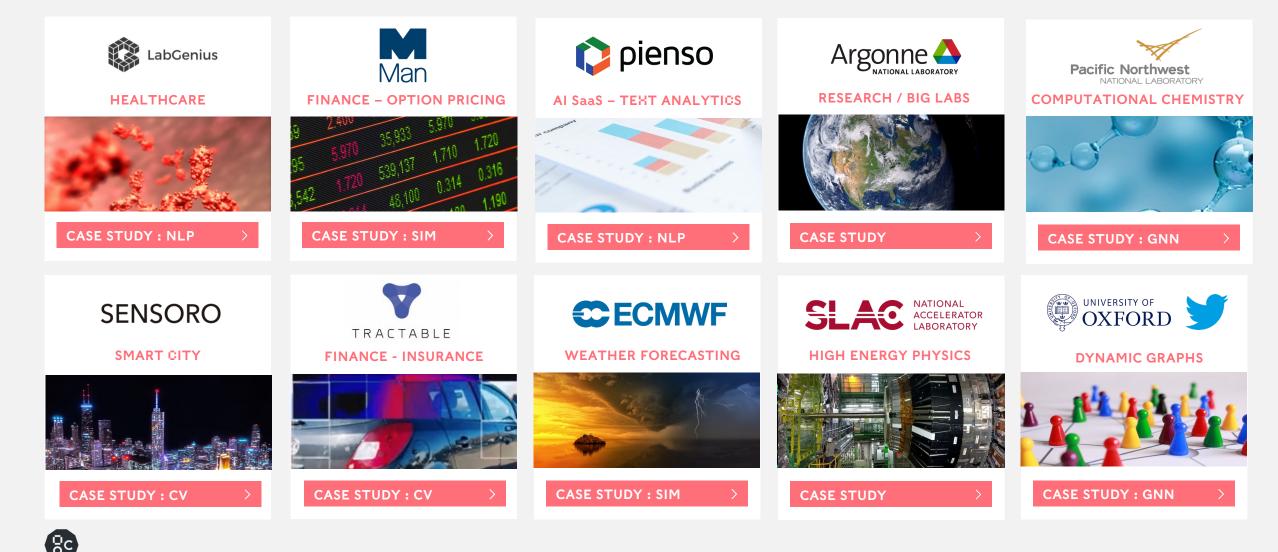
### IPU

Massively parallel MIMD. Designed for fine-grained, highperformance computing

Model and data tightly coupled, and large locally distributed SRAM

5

## **PROVEN IPU ADVANTAGE** SELECT CASE STUDIES ACROSS MANY INDUSTRIES & FIELDS



# **IPU COMPUTATIONAL ADVANTAGES**

Heterogeneous gather/scatter operations. E.g. GNNs

Group and depthwise convolutions. E.g. ResNeXt, EfficientNet

Vector operations with low arithmetic intensity. E.g. Sparse matmuls

Dense as well as Sparse Matrix Multiplication. E.g. Transformers

Hardware accelerated Random Number Generation. E.g. Random Projections

Hard to vectorize workloads. E.g. DFT in Computational Chemistry

References:

https://www.graphcore.ai/performance-results

https://www.graphcore.ai/posts/how-we-made-efficientnet-more-efficient

https://www.graphcore.ai/posts/delving-deep-into-modern-computer-vision-models

https://www.graphcore.ai/posts/training-neural-networks-in-low-dimensional-random-bases

https://www.graphcore.ai/posts/man-group-unlocks-massively-parallel-option-pricing-with-graphcore-ipu

## WORKLOADS THAT CAN'T EASILY BE VECTORIZED



Workloads with while loops that continue until convergence is achieved e.g. ray tracing



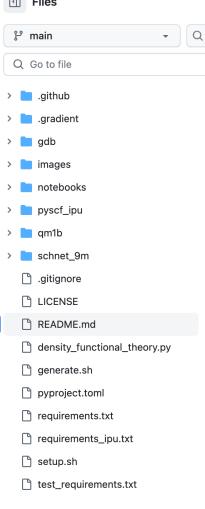
Workloads where different compute paths are required depending on the inputs e.g. DFT or CRR model



Tree-based models with unbalanced trees



#### Files



#### pyscf-ipu / README.md

Preview

Code Blame 96 lines (71 loc) · 5.32 KB

### **PySCF on IPU**

Installation guide | Example DFT Computations | Generating data | Training SchNet | QM1B dataset

📀 Run on Gradient 💭 pytest notebooks passing

#### Port of PySCF to Graphcore IPU.

Limitations

- Restricted Kohn Sham DFT (based on RKS, KohnShamDFT and hf.RHF).
- Number of atomic orbitals less than 70 mol.nao\_nr() <= 70.
- Larger numerical errors due to np.float32 instead of np.float64.
- Limited support for jax.grad(.)

#### Installation

PySCF on IPU requires Python 3.8, JAX IPU experimental, TessellateIPU library and Graphcore Poplar SDK 3.2.

To run this package on a standard CPU machine (laptop or server), install the base Python requirements:

pip install -r requirements.txt

On IPU machines, please additionally use the IPU requirements file:

pip install -U pip
pip install -r requirements\_ipu.txt

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This will configure Graphcore research experimental JAX support in your python environment.

We recommend upgrading pip to the latest stable release when using the IPU requirements. This may be an optional step depending on the overall configuration of your python environment.

And finally, make our sub-packages available:

pip install —e .

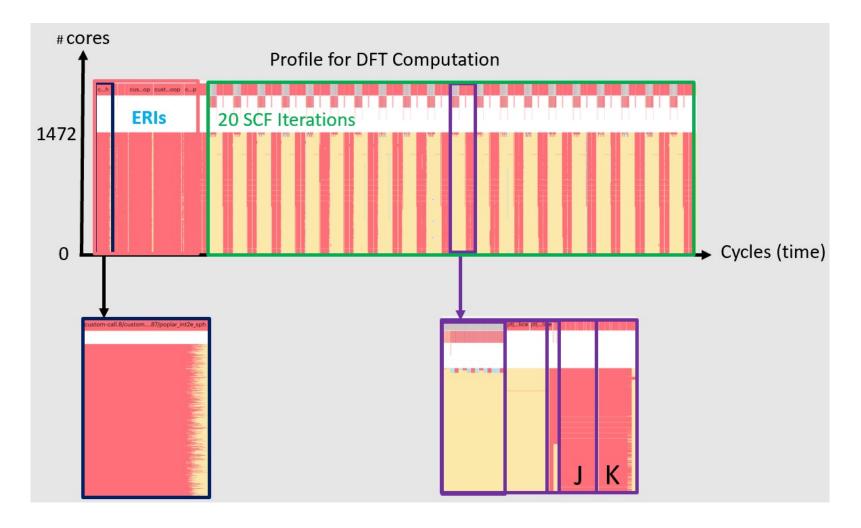
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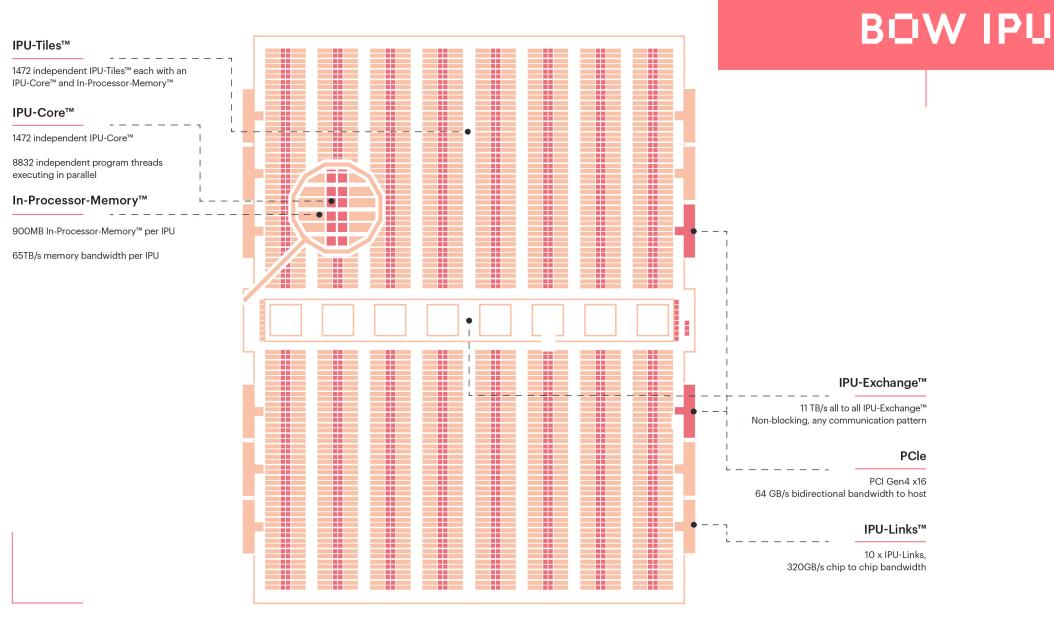
#### 😵 graphcore-research/pyscf-ipu 🗹

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	<ul> <li>D D D E</li> <li>gdb</li> <li>images</li> <li>notebooks</li> <li>DFT-dataset-generation.ipynb</li> <li>ERI-visualisation-JK.ipynb</li> <li>nanoDFT-demo.ipynb</li> <li>pyscf_ipu</li> <li>gm1b</li> </ul>	<pre>35 v def plot_orbital(orbital, mol): 36    xyzfmt = f"(len(mol.atom))\n\n" + mol.tostring() 37    v = py3Dmol.view(data=xyzfmt, style=("stick": ("radius": 0.06), "sphere": ("radius": 0.2))) 38    v.addVolumetricData(cube_data(axes, orbital), "cube", build_transferfn(orbital)) 39    return v</pre>	
().	<ul> <li>qm1b</li> <li>schnet_9m</li> <li>density_functional_theory.py</li> <li>generate.sh</li> <li>LICENSE</li> <li>pyproject.toml</li> <li>README.md</li> <li>requirements_ipu.txt</li> <li>requirements.txt</li> <li>setup.sh</li> <li>test_requirements.txt</li> </ul> Kernel sessions notebooks/nanoDFT-de	5 mol_view.spin()	
Q		SHOW MORE	
53			10

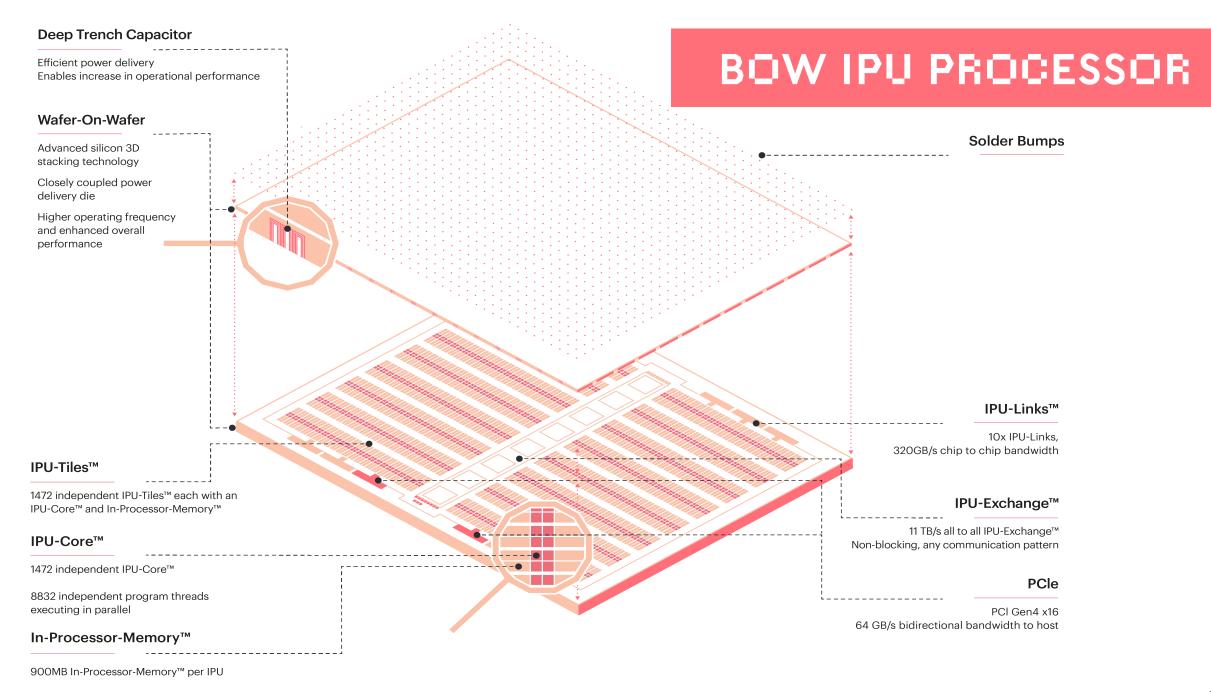


 $\begin{array}{l} \text{MIMD for} \\ E \in \mathbb{R}^{N^2 \times N^2} \end{array}$ 

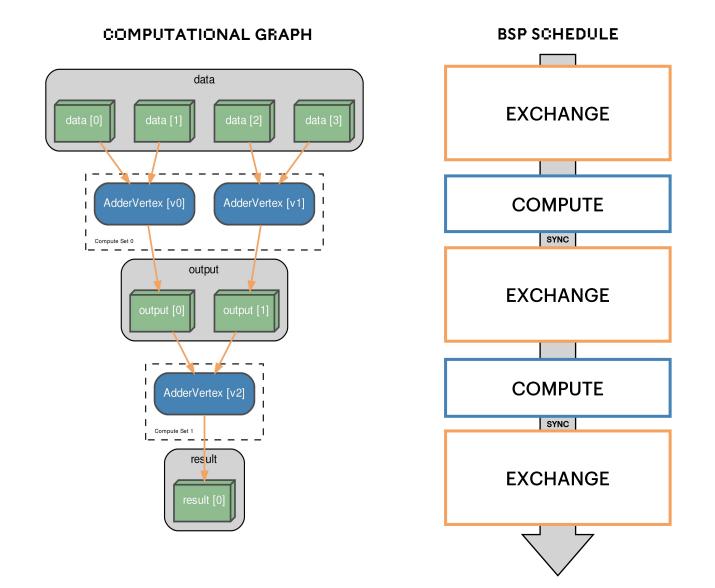
**65 TB/s** for  $J = E \cdot v \in \mathbb{R}^{N^2}$   $K = E^T \cdot v \in \mathbb{R}^{N^2}$ 







### **EXECUTION MODEL**





GRAPHCORE

## BULK SYNCHRONOUS PARALLEL (BSP)

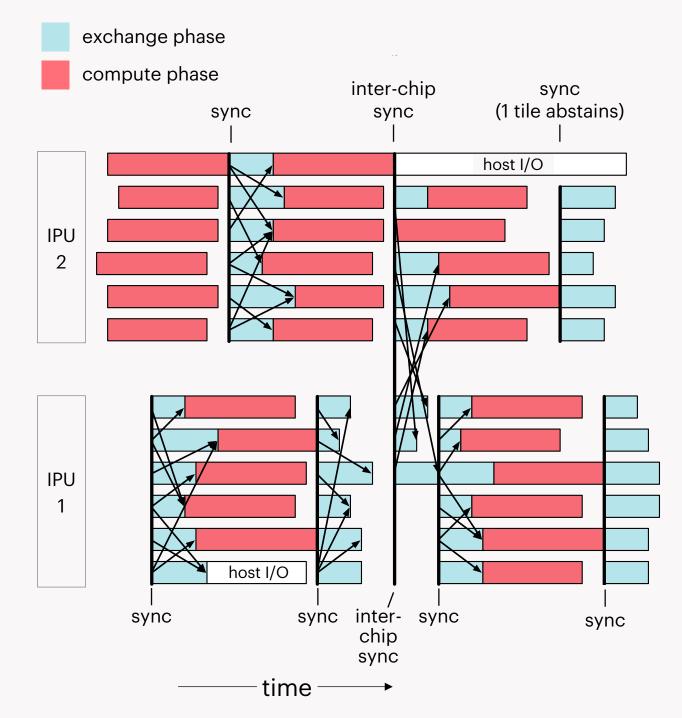
BSP software bridging model – massively parallel computing with no concurrency hazards

3 phases: compute, sync, exchange

Easy to program - no live-locks or dead-locks

Widely-used in parallel computing - Google, FB, ...

First use of BSP inside a parallel processor





# **BOW-2000 IPU MACHINE**

IU blade form factor delivering 1.4 PetaFLOPS AI Compute

Disaggregated AI/ML accelerator platform

Excellent performance & TCO leveraging In-Processor memory & IPU-Exchange

**IPU-Links scale to Bow Pod64** 

Expansion to Bow Pod256 and beyond with IPU-GW Links

## Bow **IPUs** H **IPU-Links IPU Gateway** 100GbE for host

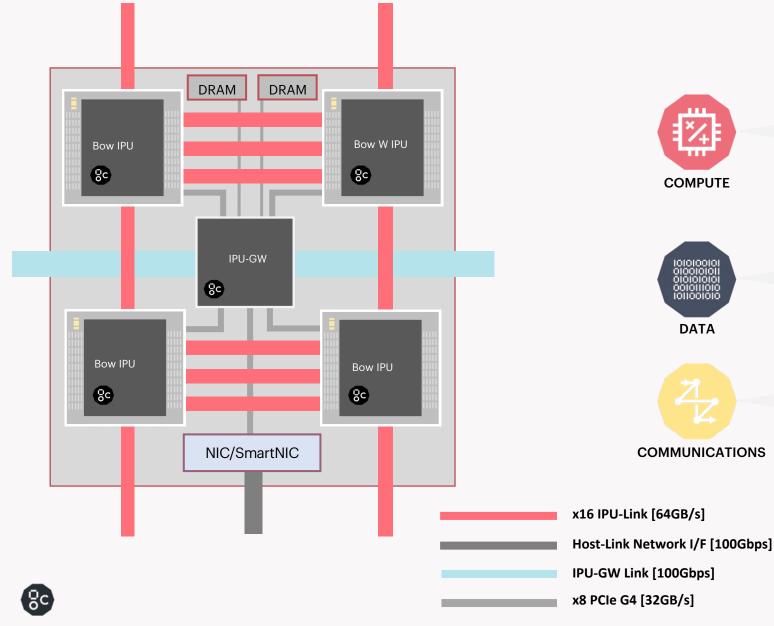
connectivity

**IPU-GW Links** 

**BOW IPU-2000** 

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## **BOW-2000: THE BUILDING BLOCK OF LARGE PODS**





COMMUNICATIONS

#### 4x Bow IPUs

- 1.4 PFLOP<sub>16</sub> compute
- 5,888 processor cores
- > 35,000 independent parallel threads

## 1010100101 01001010101 01010101010 0010111010 1011001010 DATA

#### **Exchange Memory**

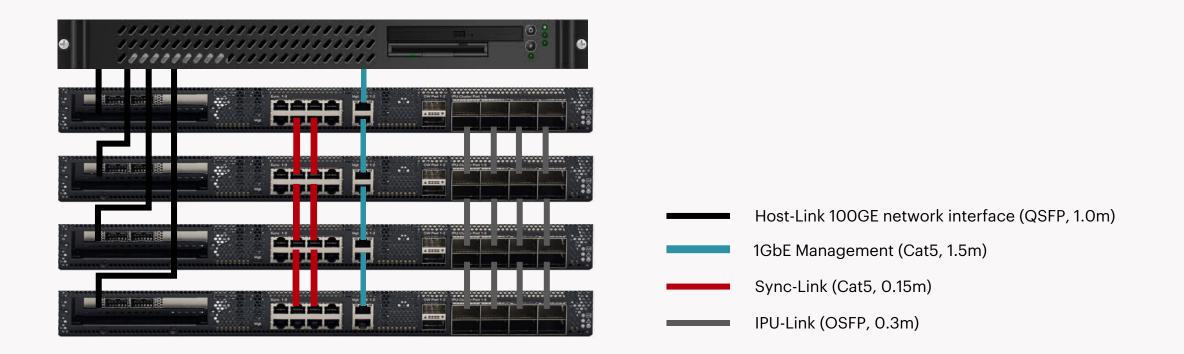
- 3.6GB In-Processor Memory @ 260 TB/s
- 128GB Streaming Memory DRAM (up to 256GB)

#### **IPU-Fabric managed by IPU-GW**

- Host-Link 100GE to Poplar Server for standard data center networking
- IPU-Link 2D Torus for intra-POD64 communication
- GW-Link 2x 100Gbps Gateway-Links for rack-torack - flexible topology

### **BOW PODIE DIRECT ATTACH**

Simple design with server with 4 Bow-2000 and 16 Bow IPUs

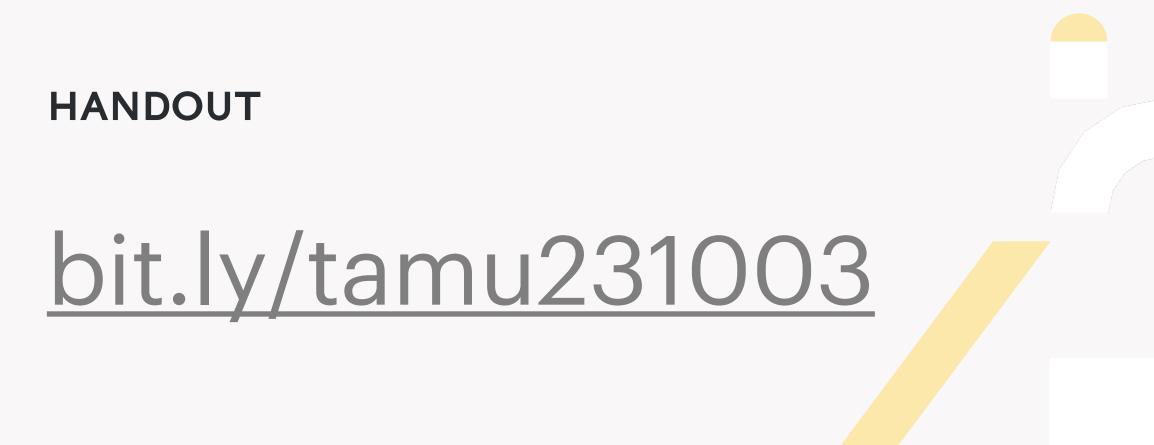


### HANDS-ON:

### **GET STARTED**

### **RUN AN EXAMPLE**







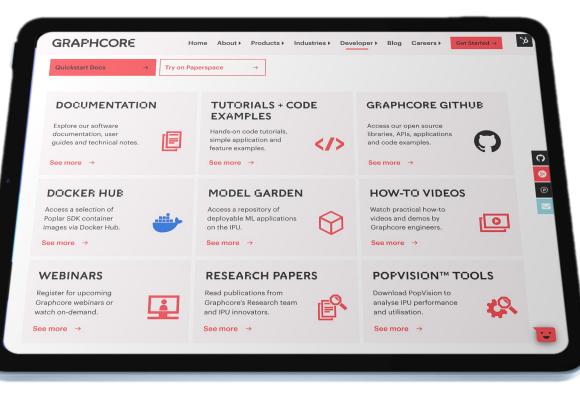
# IPU DEVELOPER ECOSYSTEM



GRAPHCORE

## **GRAPHCORE SOFTWARE ECOSYSTEM**

WORLD CLASS DEVELOPER RESOURCES FOR IPU USERS



### WWW.GRAPHCORE.AI/DEVELOPER

#### GRAPHCORE **GRAPHCORE DOCUMENTS** Graphcore Documents Version: Latest Software Hardware **Getting Started** Search docs Documents Documents Background information and Getting Started quick-start guides for Documentation for the Documentation for installing Graphcloud and Pod and using IPU-Machines and Poplar SDK and other Software Documents Pod systems systems software Hardware Documents Technical Notes and White Papers Technical Notes and Examples and **Document Updates** Examples and Tutorials White Papers Tutorials The latest news about new Document Updates Technical notes and white documents and examples Tutorials and application examples for running on the papers on Graphcore Alphabetical List of All Documents technology IPU Graphcore License Agreements



#### Getting started with PyTorch for the IPU

Running a basic model for training and inference

AI Customer Engineer, Chris Bogdiukiewicz introduces PyTorch for the IPU. With PopTorch™ - a simple Python wrapper for PyTorch programs, developers can easily run models, directly on Graphcore IPUs with a few lines of extra code.

Get the Code  $\rightarrow$ 

In this video, Chris provides a quick demo on running a basic model for both training and inference using a MNIST based example.

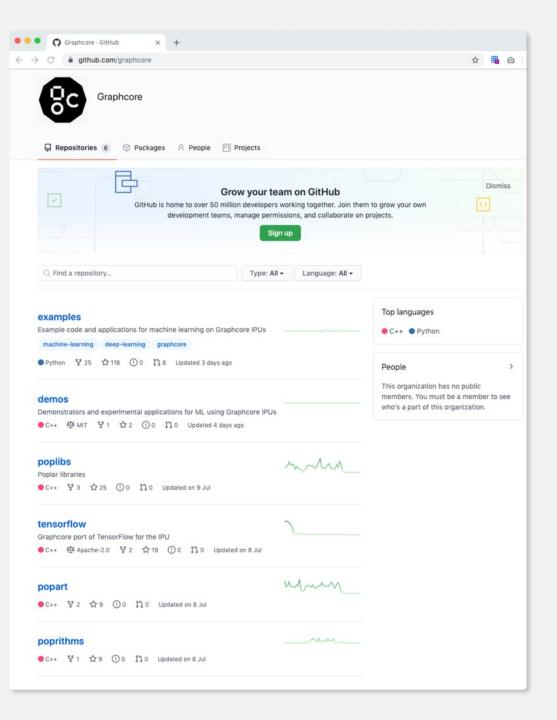
Read the Guide  $\rightarrow$ 



### **OPEN SOURCE**

### github.com/graphcore

- As part of our ethos to put power in the hands of AI developers, Graphcore open sourced in 2020
- PopLibs<sup>™</sup>, PopART, PyTorch & TensorFlow for IPU fully open source and available on GitHub
- Our code is public and open for code contributions from the wider ML developer community





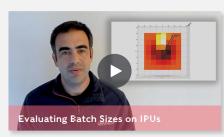
### **VIDEO + GITHUB TUTORIALS**

### A comprehensive set of online developer training materials and educational content



Bulk Synchronous Parallel E

Getting started with PopVision





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Learn how to create and run programs using Poplar and PopLibs with our hands-on programming tutorials.					
Programs and Variables	Using PopLibs	Writing Vertex Code			
Profiling Output	Basic Machine Learning Example	Matrix-Vector Multiplication			
Matrix-Vector Multiplication Optimisation	Simple PyTorch for the IPU	w			

#### **Tutorial 1: programs and variables**

Copy the file tut1 variables/start\_here/tut1.cpp to your working directory and open it in an editor. The file contains the outline of a C++ program including some Poplar library headers and a namespace.

#### Graphs, variables and programs

All Poplar programs require a Graph object to construct the computation graph. Graphs are always created for a specific target (where the target is a description of the hardware being targeted, such as an IPU). To obtain the target we need to choose a device.

The tutorials use a simulated target by default, so will run on any machine even if it has no Graphcore hardware attached. On systems with accelerator hardware, the header file poplar/DeviceManager.hpp contains API calls to enumerate and return Device objects for the attached hardware.

Simulated devices are created with the IPUModel class, which models the functionality of an IPU on the host. The createDevice function creates a new virtual device to work with. Once we have this device we can create a Graph object to target it.

· Add the following code to the body of main :

// Create the IPU Model device IPUModel ipuModel; Device device = ipuModel.createDevice(); Target target = device.getTarget();

// Create the Graph object Graph graph(target):

Any program running on an IPU needs data to work on. These are defined as variables in the graph.

#### · Add the following code to create the first variable in the program:

#### Tutorial 5: a basic machine learning example

This tutorial contains a complete training program that performs a logistic regression on the MNIST data set, using gradient descent. The files for the demo are in tut5\_ml. There are no coding steps in the tutorial. The task is to understand the code, build it and run it. You can build the code using the supplied makefile.

Before you can run the code you will need to run the get\_mnist.sh script to download the MNIST data.

The program accepts an optional command line argument to make it use the IPU hardware instead of a simulated IPU.

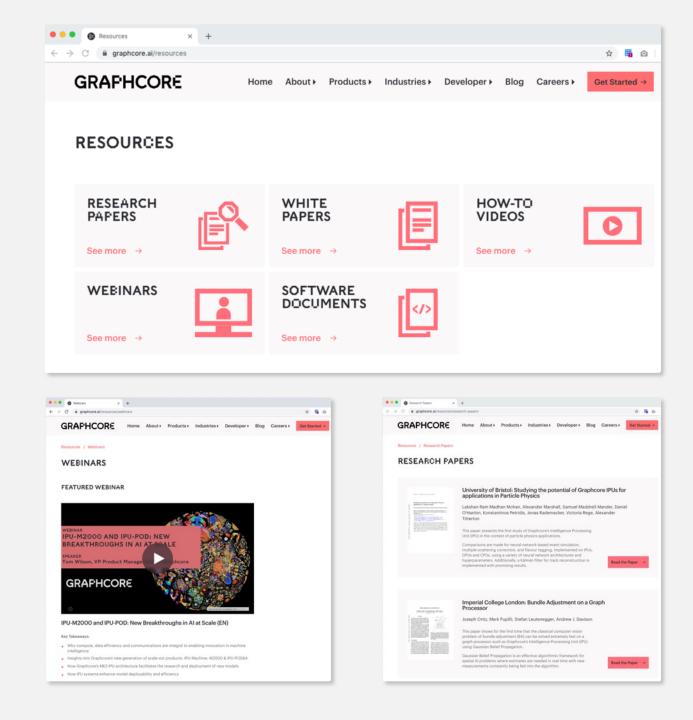
As you would expect, training is significantly faster on the IPU hardware.

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### **RESOURCES CENTRE**

### graphcore.ai/resources

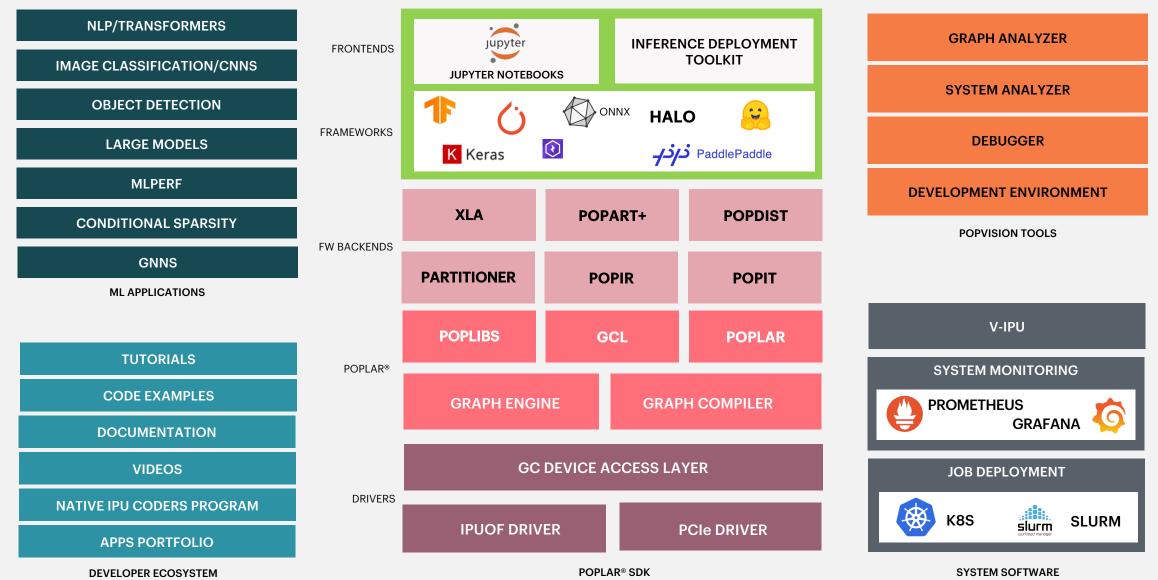
- Central source of research papers, white papers, videos, on-demand webinars and documentation
- Product resources for ML Engineers & IT / Infrastructure Managers now available





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## **GRAPHCORE SOFTWARE**





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### ENHANCED MODEL GARDEN

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# PUBLIC ACCESS TO WIDE VARIETY OF MODELS, READY TO RUN ON IPU

### **NEW FILTER/SEARCH CAPABILITY**

### DIRECT ACCESS TO GITHUB

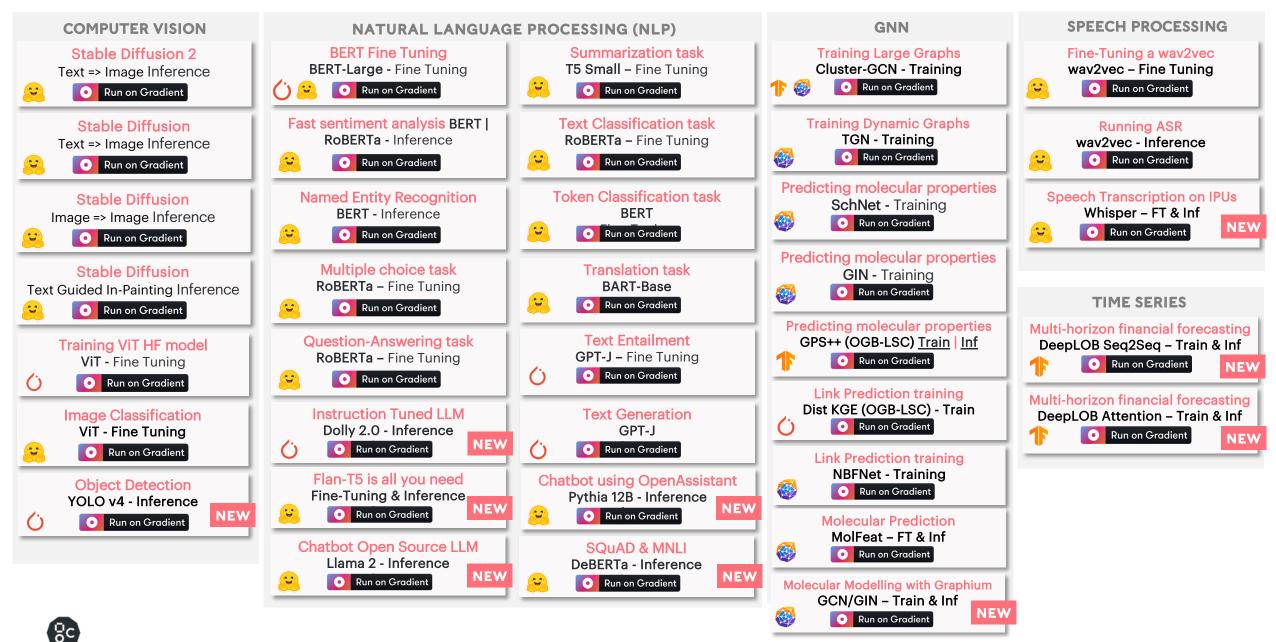
### PAPERSPACE NOTEBOOK LINKS

https://www.graphcore.ai/resources/model-garden

### 

### Access IPU-ready notebooks in seconds

Paperspace



https://www.graphcore.ai/ipu-jupyter-notebooks

### **USEFUL ENV VARIABLES**





Logging messages can be generated when your program runs. This is controlled by the environment variables described below. For more detailed information see the docs: <u>https://docs.graphcore.ai/projects/poplar-user-guide/en/latest/env-vars.html</u>

POPLAR\_LOG\_LEVEL: Enable logging for Poplar

POPLAR\_LOG\_DEST: Specify the destination for Poplar logging ("stdout", "stderr" or a file name)

"OFF"	No logging information. The default.
"ERR"	Only error conditions will be reported.
"WARN"	Warnings when, for example, the software cannot achieve what was requested (for example, if the convolution planner can't keep to the memory budget, or Poplar has determined that the model won't fit in memory but the debug.allowOutOfMemory option is enabled).
"INFO"	Very high level information, such as PopLibs function calls.
"DEBUG"	Useful per-graph information.
"TRACE"	The most verbose level. All useful per-tile information.

## **CREATE EXECUTION PROFILE**

POPLAR\_ENGINE\_OPTIONS='{"autoReport.all":"true", "autoReport.directory":"./report"}'

- The PopVision Graph Analyser uses report files generated during compilation and execution by the Poplar SDK.
- These files can be created using POPLAR\_ENGINE\_OPTIONS.
- In order to capture the reports needed for the PopVision Graph Analyser you only need to set POPLAR\_ENGINE\_OPTIONS='{"autoReport.all":"true"}' before you run a program. By default this will enable instrumentation and capture all the required reports to the current working directory.

## **EXECUTABLE CACHE**

If you often run the <u>same models</u> you might want to enable executable caching to save time:

**POPTORCH:** 

• You can do this by either setting the POPTORCH\_CACHE\_DIR environment variable or by calling poptorch.Options.enableExecutableCaching.

TENSORFLOW:

• You can use the flag --executable\_cache\_path to specify a directory where compiled files will be placed. Fused XLA/HLO graphs are hashed with a 64-bit hash and stored in this directory.

### Warning

The cache directory might grow large quickly. Poplar doesn't evict old models from the cache and, depending on the number and size of your models and the number of IPUs used, the executables might be quite large. It is the your responsibility to delete the unwanted cache files.

## SYNTHETIC-DATA

TF\_POPLAR\_FLAGS= "--use\_synthetic\_data --synthetic\_data\_initializer=random"

Used for measuring the IPU-only throughput and disregards any host/CPU activity.

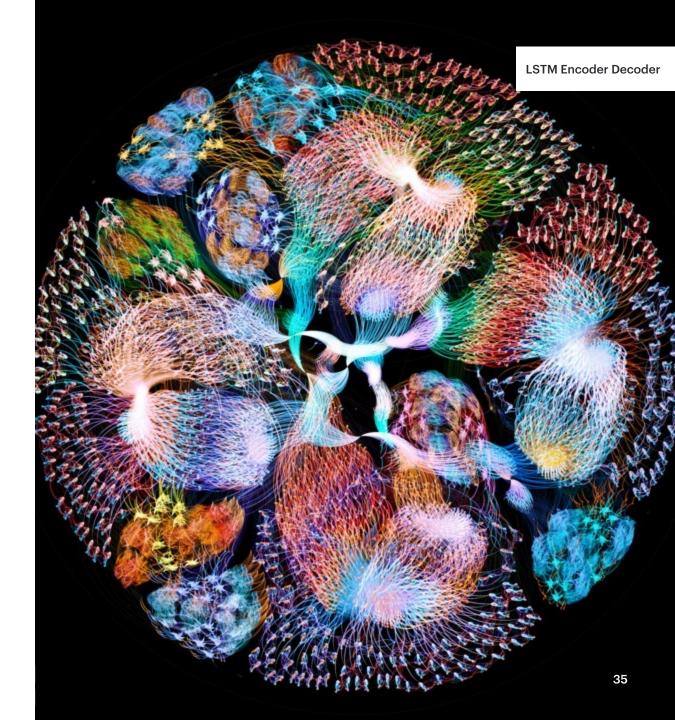
## **GRAPHCORE COMMAND LINE TOOLS**

gc-docker Allows you to use IPU devices in Docker containers using the Docker container engine.

- *gc-flops* Allows you to benchmark the number of floating point operations per second on one or more IPU processors.
- gc-info Determines what IPU cards are present in the system.
- gc-inventory Lists device IDs, physical parameters and firmware version numbers.
- *gc-links* Displays the status and connectivity of each of the IPU-Links that connect IPUs. See also *IPU-Link channel mapping* for connectivity in an IPU Server containing C2 cards.
- gc-monitor Monitors IPU activity on shared systems.
- gc-reset Resets IPU devices.
- gc-exchangetest Allows you to test the internal exchange fabric in an IPU.
- gc-exchangewritetest Tests direct writes to the IPU's tile memory via the host.
- gc-gwlinkstraffictest Tests GW-Links on multi-rack IPU-POD systems.
- *gc-hostsynclatencytest* Reports the latency of transfers between the host machine and the IPUs (in both directions).
- gc-hosttraffictest Allows you to test the data transfer between the host machine and the IPUs (in both directions).
- gc-iputraffictest Allows you to test the data transfer between IPUS.
- gc-memorytest Tests all the memory in an IPU, reporting any tiles that fail.
- gc-podman Allows you to use IPU devices in Docker containers using the Podman container engine.
- gc-powertest Tests power consumption and temperature of the IPU processors.



### **TF2/KERAS ON IPU**



## **KERAS ON IPU**

IPU optimized Keras Model and Sequential with the following features:

- On-device training loop for reduction of communication overhead.
- Gradient accumulation for simulating larger batch sizes.
- Automatic data-parallelisation of the model when placed on a multi-IPU device.



gpu_cnn_keras.py ↔ ipu_cnn_keras.py tf_keras	
s stf	<pre>import tensorflow as tf</pre>
Keras ras.layers import *	from tensorflow keras layers import *
Relas GPU	+ from tensorflow.python import ipu
	+ cfg = ipu.config.IPUConfig()
	+ cfg.auto_select_ipus = 1
	<pre>+ cfg.configure_ipu_system() + with ipu.ipu_strategy.IPUStrategy().scope():</pre>
<pre>(x_train, y_train), (x_test, y_test) = tf.keras.datasets.cifar10.load_data()</pre>	<pre>+ with ipu.ipu_strategy.iPustrategy().scope():     (x_train, y_train), (x_test, y_test) = tf.keras.datasets.cifar10.load_data()</pre>
<pre>x_train = x_train.astype('float32') / 255.0</pre>	x_train = x_train.astype('float32') / 255.0
<pre>y_train = tf.keras.utils.to_categorical(y_train, 10) da train = tf.data_Dataset_from tensor aliese((y_train, y_train)) batch(64_dram_remainds))</pre>	<pre>y_train = tf.keras.utils.to_categorical(y_train, 10) da_train = tf_data_Dataset_from tensor_alises((x_train, x_train)) hetch(64_dran_renue)</pre>
<pre>ds_train = tf.data.Dataset.from_tensor_slices((x_train, y_train)).batch(64, drop_remainde</pre>	<pre>ds_train = tf.data.Dataset.from_tensor_slices((x_train, y_train)).batch(64, drop_rema</pre>
<pre>model = tf.keras.Sequential([</pre>	<pre>model = tf.keras.Sequential([</pre>
<pre>Conv2D(32, (3, 3), padding='same', input_shape=x_train.shape[1:]),</pre>	<pre>Conv2D(32, (3, 3), padding='same', input_shape=x_train.shape[1:]),</pre>
Activation('relu'),	Activation('relu'),
Conv2D(32, (3, 3)),	Conv2D(32, (3, 3)),
Activation('relu'),	Activation('relu'),
<pre>MaxPooling2D(pool_size=(2, 2)),</pre>	<pre>MaxPooling2D(pool_size=(2, 2)),</pre>
Dropout(0.25),	Dropout(0.25),
Conv2D(64, (3, 3), padding='same'),	Conv2D(64, (3, 3), padding='same'),
Activation('relu'),	Activation('relu'),
Conv2D(32, (3, 3)),	Conv2D(32, (3, 3)),
Activation('relu'),	Activation('relu'),
<pre>MaxPooling2D(pool_size=(2, 2)),</pre>	<pre>MaxPooling2D(pool_size=(2, 2)),</pre>
Dropout(0.25),	Dropout(0.25),
<pre>Flatten(),</pre>	<pre>Flatten(),</pre>
Dense(512),	Dense(512),
Activation('relu'),	Activation('relu'),
Dropout(0.5),	Dropout(0.5),
Dense(10),	Dense(10),
<pre>Activation('softmax')</pre>	<pre>Activation('softmax')</pre>
1)	1)
<pre>model.compile(loss='categorical_crossentropy',</pre>	<pre>model.compile(loss='categorical_crossentropy',</pre>
<pre>optimizer=tf.optimizers.SGD(learning_rate=0.016), </pre>	<pre>optimizer=tf.optimizers.SGD(learning_rate=0.016),</pre>
<pre>metrics=['accuracy'])</pre>	<pre>metrics=['accuracy'])</pre>
<pre>model.fit(ds_train, epochs=40)</pre>	<pre>model.fit(ds_train, epochs=40)</pre>

.

# **TF2/KERAS TUTORIALS**

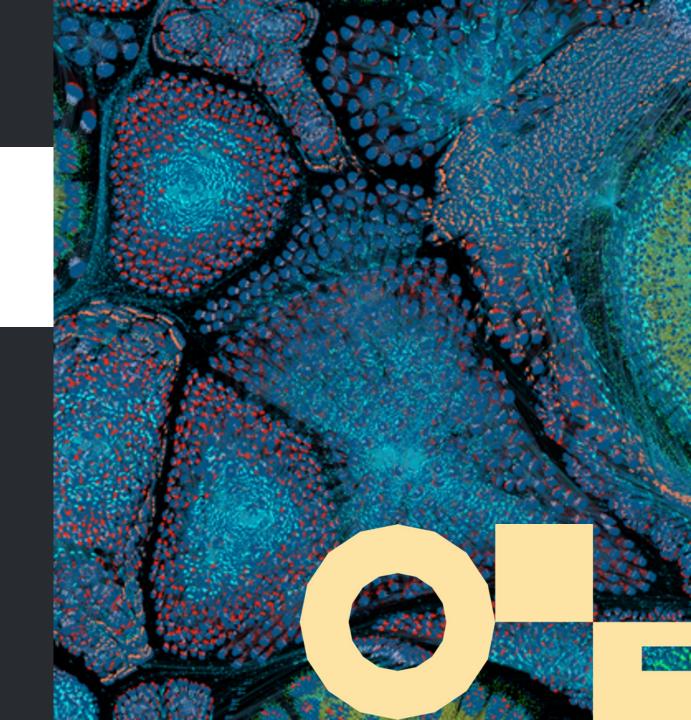
Continued in the repositories below (follow the READMEs)

github.com/graphcore/examples/tree/master/tutorials/tutorials/tensorflow2/keras

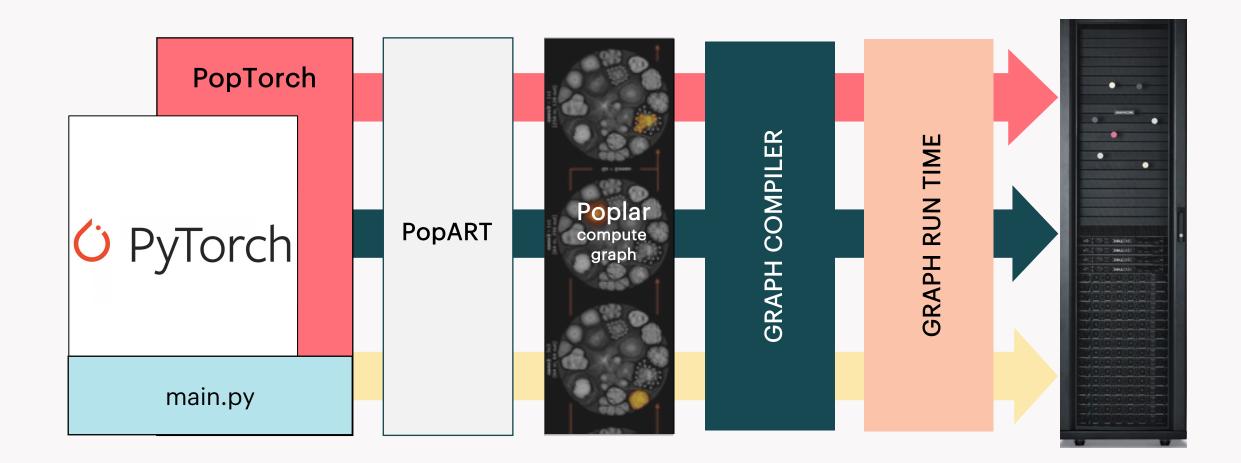


# **INTRO TO POPTORCH**

# GRAPHCORE



### WHAT IS POPTORCH?



## WHAT IS POPTORCH?

- PopTorch is a set of extensions for PyTorch to enable PyTorch models to run on Graphcore's IPU hardware.
- PopTorch supports both inference and training. To run a model on the IPU you wrap your existing PyTorch model in either a PopTorch inference wrapper or a PopTorch training wrapper.
- You can provide further annotations to partition the model across multiple IPUs. Using the
  user-provided annotations, PopTorch will use <u>PopART</u> to parallelise the model over the given
  number of IPUs.
- Additional parallelism can be expressed via a replication factor which enables you to dataparallelise the model over more IPUs.



## **PYTORCH FOR IPU**

**O** PyTorch

Define a model within PyTorch Create an IPU execution wrapper around the model and run as normal PopTorch uses PyTorch dispatcher to trace the model Compile the graph in PopART and then run on one or more IPUs

## **GETTING STARTED: TRAINING A MODEL**





# **TRAINING A MODEL**

1. Import packages

PopTorch is a separate package from PyTorch, and must be imported.

2. Load dataset using torchvision.datasets and poptorch.DataLoader

In order to make data loading easier and more efficient, PopTorch offers an extension of torch.utils.data.DataLoader class: poptorch.DataLoader class is specialised for the way the underlying PopART framework handles batching of data.

### 3. Define model and loss function using torch API

The only difference here from pure PyTorch is the loss computation, which has to be part of the forward function. This is to ensure the loss is computed on the IPU and not on the CPU, and to give us as much flexibility as possible when designing more complex loss functions.



# **TRAINING A MODEL**

### 4. Prepare training

Instantiate compilation and execution options, these are used by PopTorch's wrappers such as poptorch.DataLoader and poptorch.trainingModel.

5. Train the model

Define the optimizer using PyTorch's API.

Use poptorch.trainingModel wrapper, to wrap your PyTorch model. This wrapper will trigger the compilation of our model, using TorchScript, and manage its translation to a program the IPU can run. Then run your training loop.



	_, ind = corch.max(predictions, i)		_, ind = coren.max(predictions, i)
	<pre># provide labels only for samples, where prediction is available (during the training, no ions.size()[0]:]</pre>		<pre># provide labels only for samples, where prediction is available (during the training, not labels = labels[-predictions.size()[0]:]</pre>
	PyTorch <sup>ch.eq(ind, labels)).item() / labels.size(GPU</sup>		<pre>accuracy = torch.sum(torch.eq(ind, labels)).item() / labels.si IPU I00.0 return accuracy</pre>
	ifname == 'main':	i	.fname == 'main':
	<pre>parser = argparse.ArgumentParser(description='MNIST training in PopTorch')</pre>		<pre>parser = argparse.ArgumentParser(description='MNIST training in PopTorch')</pre>
	<pre>parser.add_argument('batch-size', type=int, default=8, help='batch size for training (default=1)</pre>		parser.add_argument('batch-size', type=int, default=8, help='batch size for training (de
	<pre>parser.add_argument('test-batch-size', type=int, default=8, help='batch size for testing</pre>		<pre>parser.add_argument('test-batch-size', type=int, default=8, help='batch size for testing</pre>
	<pre>parser.add_argument('epochs', type=int, default=10, help='number of epochs to train (de</pre>		<pre>parser.add_argument('epochs', type=int, default=10, help='number of epochs to train (definition of epochs)</pre>
	<pre>parser.add_argument('lr', type=float, default=0.05, help='learning rate (default: 0.05)</pre>		<pre>parser.add_argument('lr', type=float, default=0.05, help='learning rate (default: 0.05)'</pre>
		+	<pre>parser.add_argument('device-iterations', type=int, default=50, help='device iterations   args = parser.parse args()</pre>
	args = parser.parse_args()		arys – parser.parse_arys()
-	<pre>training_data = torch.utils.data.DataLoader(</pre>	+	<pre>opts = poptorch.Options().deviceIterations(args.device_iterations)</pre>
	///////////////////////////////////////	+	<pre>training_data = poptorch.DataLoader(opts,</pre>
	<pre>torchvision.datasets.MNIST('mnist_data/', train=True, download=True,</pre>		<pre>torchvision.datasets.MNIST('mnist_data/', train=True, download=True, trans</pre>
	<pre>batch_size=args.batch_size, shuffle=True, drop_last=True) test_data = torch.utils.data.DataLoader(</pre>	+	<pre>batch_size=args.batch_size, shuffle=True, drop_last=True) test_data = poptorch.DataLoader(opts,</pre>
	torchvision.datasets.MNIST('mnist_data/', train=False, download=True,		torchvision.datasets.MNIST('mnist_data/', train=False, download=True, train
	<pre>model = Network()</pre>		<pre>model = Network()</pre>
	<pre>training_model = TrainingModelWithLoss(model)</pre>		<pre>training_model = TrainingModelWithLoss(model)</pre>
	<pre>optimizer=optim.SGD(model.parameters(), lr=args.lr)</pre>		<pre>optimizer=optim.SGD(model.parameters(), lr=args.lr)</pre>
		+	<pre>training_model = poptorch.trainingModel(training_model, opts, optimizer=optimizer)</pre>
í		+	<pre>inference_model = poptorch.inferenceModel(model)</pre>
	# Run training		# Run training
	for _ in range(args.epochs):		for _ in range(args.epochs):
	for data, labels in training_data:		for data, labels in training_data:
	preds, losses = training_model(data, labels)		<pre>preds, losses = training_model(data, labels)</pre>
—	<pre>optimizer.zero_grad()</pre>	+	
-	losses.backward()	+	# Detach the training model so that the same IPU could be used for validation
—	<pre>optimizer.step()</pre>	+	<pre>training_model.detachFromDevice()</pre>
	# Run validation		# Run validation
	sum acc = $0.0$		sum_acc = 0.0
	with torch.no_grad():		<pre>with torch.no_grad():</pre>
	for data, labels in test_data:		for data, labels in test_data:
—	<pre>output = model(data)</pre>	+	<pre>output = inference_model(data)</pre>
	<pre>sum_acc += accuracy(output, labels)</pre>		<pre>sum_acc += accuracy(output, labels)</pre>
	<pre>print("Accuracy on test set: {:0.2f}%".format(sum_acc / len(test_data)))</pre>		<pre>print("Accuracy on test set: {:0.2f}%".format(sum_acc / len(test_data)))</pre>

# **POPTORCH.OPTIONS**

- The compilation and execution on the IPU can be controlled using poptorch.Options
- Full list of options available here: <u>https://docs.graphcore.ai/projects/poptorch-user-guide/en/latest/overview.html#options</u>
- Some examples:

### (i) deviceIterations

This option specifies the number of batches that is prepared by the host (CPU) for the IPU. The higher this number, the less the IPU has to interact with the CPU, for example to request and wait for data, so that the IPU can loop faster. However, the user will have to wait for the IPU to go over all the iterations before getting the results back. The maximum is the total number of batches in your dataset, and the default value is 1.

### (ii) replicationFactor

This is the number of replicas of a model. We use replicas as an implementation of data parallelism. To achieve the same behavior in pure PyTorch, you'd wrap your model with torch.nn.DataParallel, but with PopTorch, this is an option.

# **POPTORCH TUTORIALS**

Continued in the repositories below (follow the READMEs)

github.com/graphcore/examples/tree/master/tutorials/tutorials/pytorch/basics

github.com/graphcore/examples/tree/master/tutorials/tutorials/pytorch/mixed\_precision

github.com/graphcore/examples/tree/master/tutorials/tutorials/pytorch/efficient\_data\_loading

github.com/graphcore/examples/tree/master/tutorials/tutorials/pytorch/pipelining





A POWERFUL AND FLEXIBLE OPEN-SOURCE PYTHON LIBRARY FOR TRAINING MOLECULAR GNNS AT SCALE

# **GRAPHIUM FOR IPU**

Graphium integrates state-of-the-art Graph Neural Network (GNN) architectures and a user-friendly API, enabling the easy construction and training of custom GNN models.

#### ANNOUNCEMENT | TECHNICAL BLOG | GETTING STARTED



#### RUN GRAPHIUM ON IPU WITH PAPERSPACE JUPYTER NOTEBOOK





# **PyG is the ultimate library** for Graph Neural Networks

Build graph learning pipelines with ease



HARVARD MEDICAL SCHOOL

pyg.org

"The suitability of IPUs for running GNNs and the kind of performance advantage that Graphcore and its customers have demonstrated is really helping to accelerate the uptake of this exciting model class" Matthias Fey – PyG creator & founder of Kumo.ai

# **PYTORCH GEOMETRIC FOR IPU**

#### ANNOUNCEMENT | TECHNICAL BLOG | GETTING STARTED



#### RUN GNN MODELS IN PYG ON PAPERSPACE JUPYTER NOTEBOOKS



POPLAR<sup>TM</sup> POPVISION TOOLS

## POPVISION<sup>TM</sup> TOOLS

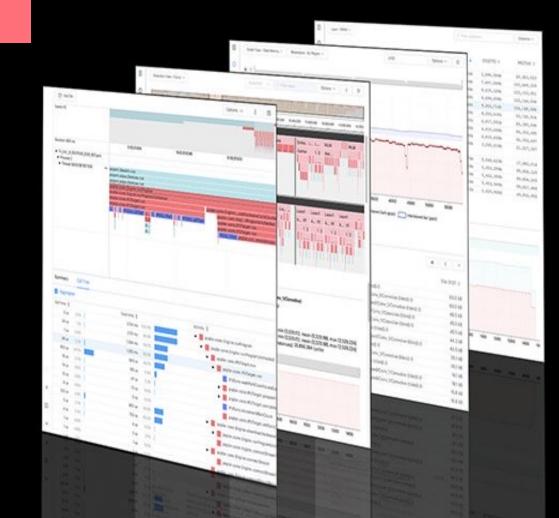
### **GRAPH ANALYSER**

Useful for analysing and optimising the memory use and execution performance of ML models on the IPU

### SYSTEM ANALYSER

Ъс

Graphical view of the timeline of host-side application execution steps



"Our team was very impressed by the care and effort Graphcore has clearly put into the PopVision graph and system analysers. It's hard to imagine getting such a helpful and comprehensive profiling of the code elsewhere, so this was really a standout feature in our IPU experience."

Dominique Beaini, Valence Discovery, a leader in AI-first drug design

## **POPVISION TOOLS**

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#### IPU MEMORY ANALYSIS

Capture memory information from your ML models when executed on IPUs. Inspect variable placement, size and liveness throughout the execution.



#### EXECUTION TRACE REPORT

View the output of instrumenting a Poplar program, capturing cycle counts for each step. See execution statistics, tile balance, cycle proportions and compute-set details.

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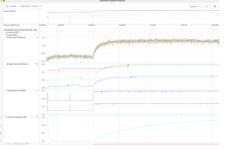
#### **REPORT COMPARISONS**

Open two reports at once to compare their memory, execution, liveness and operations. Visualise where efficiencies can be made with different model parameters.



#### HOST EXECUTION ANALYSIS

Understand the execution of IPU-targeted software on your host system processors. Identify any bottlenecks between CPUs and IPUs across a visual interactive timeline.



#### GRAPH DATA

Plot graph data of any numerical data points from the host or IPU processor systems, such as board temperature, power consumption and IPU utilisation.

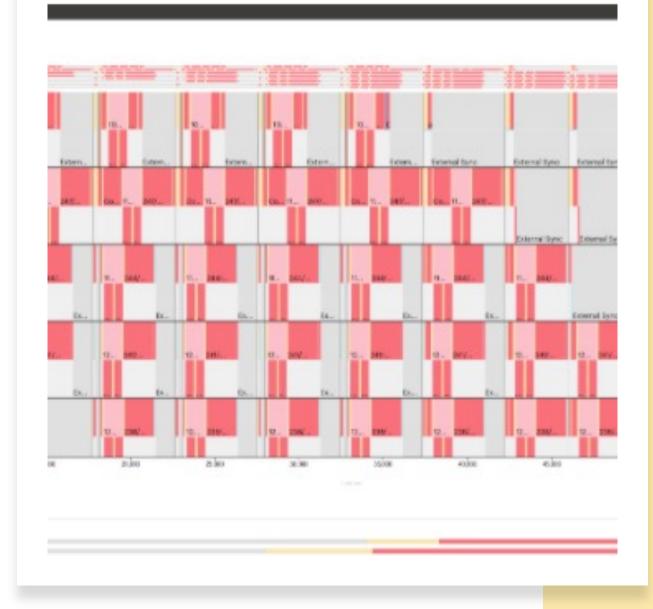
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#### LOCAL + REMOTE REPORTS

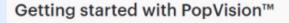
Ability to open reports either on your local machine, or remotely on the host machine. The Graph Analyser also supports local and remote report access.

## POPVISION GRAPH ANALYSER

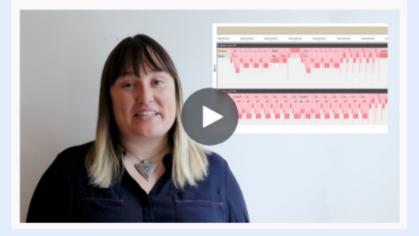
- You can use the PopVision Graph Analyser tool to debug IPU programs and generate reports on compilation and execution of the program.
- This tool can be downloaded from graphcore.ai/downloads
- There is a built-in help system within the tool for any questions you might have about producing and analysing reports.



# **PopVision Graph Analyser**



Intro to the PopVision<sup>™</sup> Graph Analyser



Getting started video available on the developers portal

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Several new features including:

- A new file format for the graph and execution profile, resulting in a 50% file size reduction
- Enhanced PopLibs debug information

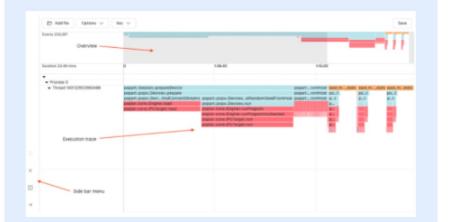
#### **Liveness Report**

The debug information shown for a variable now displays enhanced information. For each variable that has debug information, you can now see the PopLibs API that created it, its arguments and its outputs.

Enhanced debug information has been added to program steps. Program steps show Poplar and PopLibs debug information such as which PopLibs API created that program step, its arguments and its outputs.

Check out the integrated help or visit our developer portal for more information

# **PopVision System Analyser**



D. poplar::core::..gramUnchecked D. poplar::core:::.gramUnchecked D. poplar::core:::.PUTarget::run Duration: 35:833 secs Channel: Poplar Show the execution of the software on the host processor enabling users to identify bottlenecks in execution between CPU & IPU(s).

Provide profile insights as you scale models to multiple CPUs / IPUs.

The PopVision System Analyser allows developers to understand the execution of programs running on the host processor which control the IPU(s). The System Analyser shows the interaction between the host and the IPU(s) so that developers can understand where the bottlenecks are in the execution of their applications.

The PopVision System Analyser visualises the information collected by the PopVision Trace Instrumentation Library which is part of the Poplar SDK.

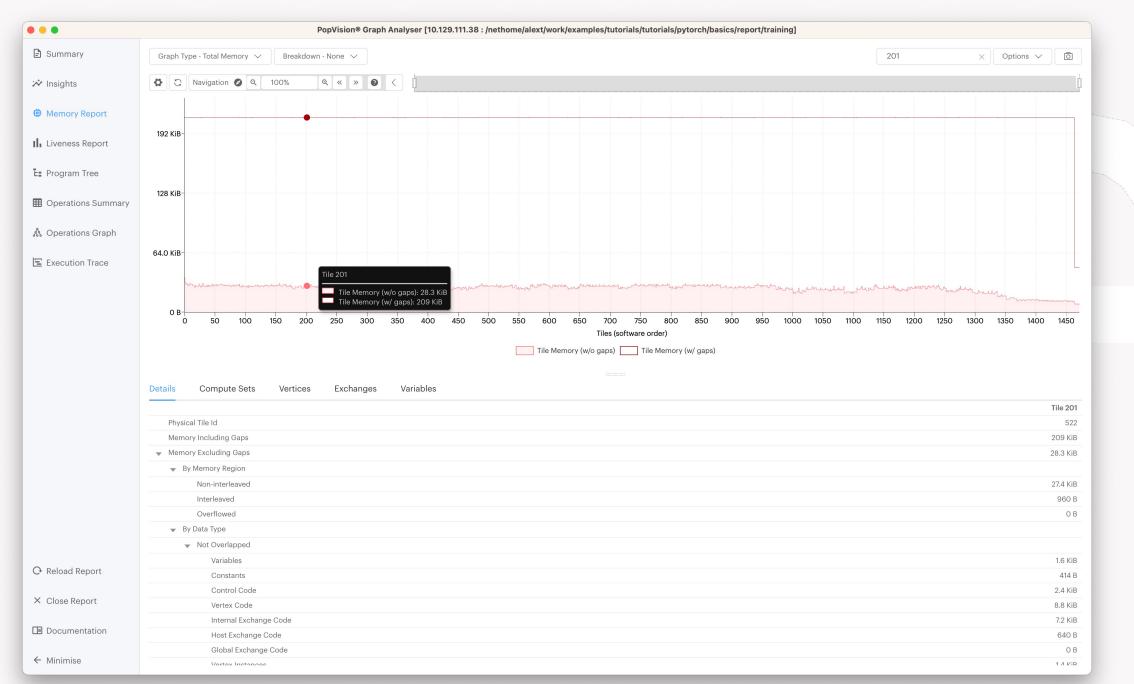
Visit our developer portal for more information and the latest documentation:

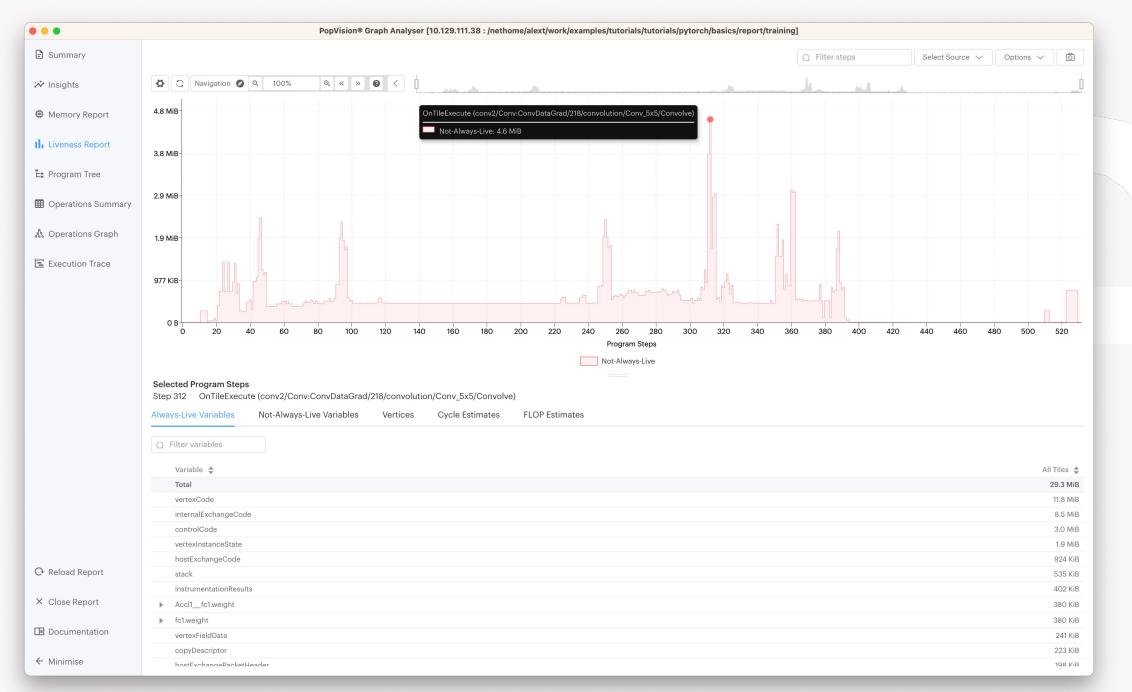
https://www.graphcore.ai/developer

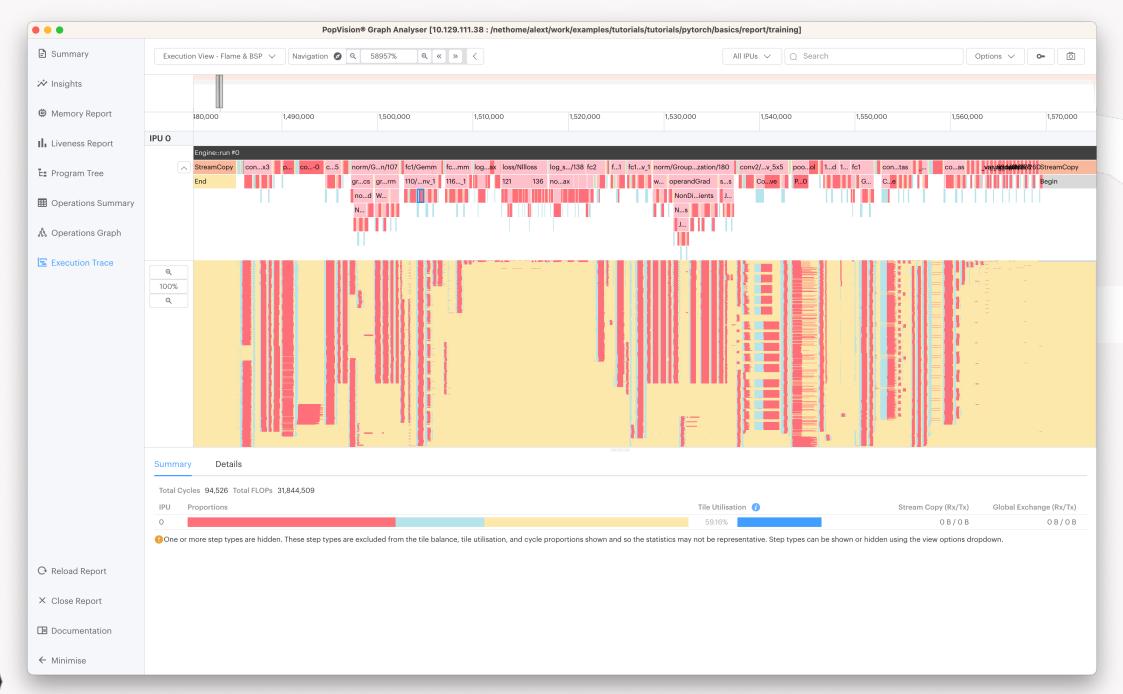
## **CREATE PROFILE**

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# **POPVISION TUTORIALS**

Continued in the repositories below (follow the READMEs)

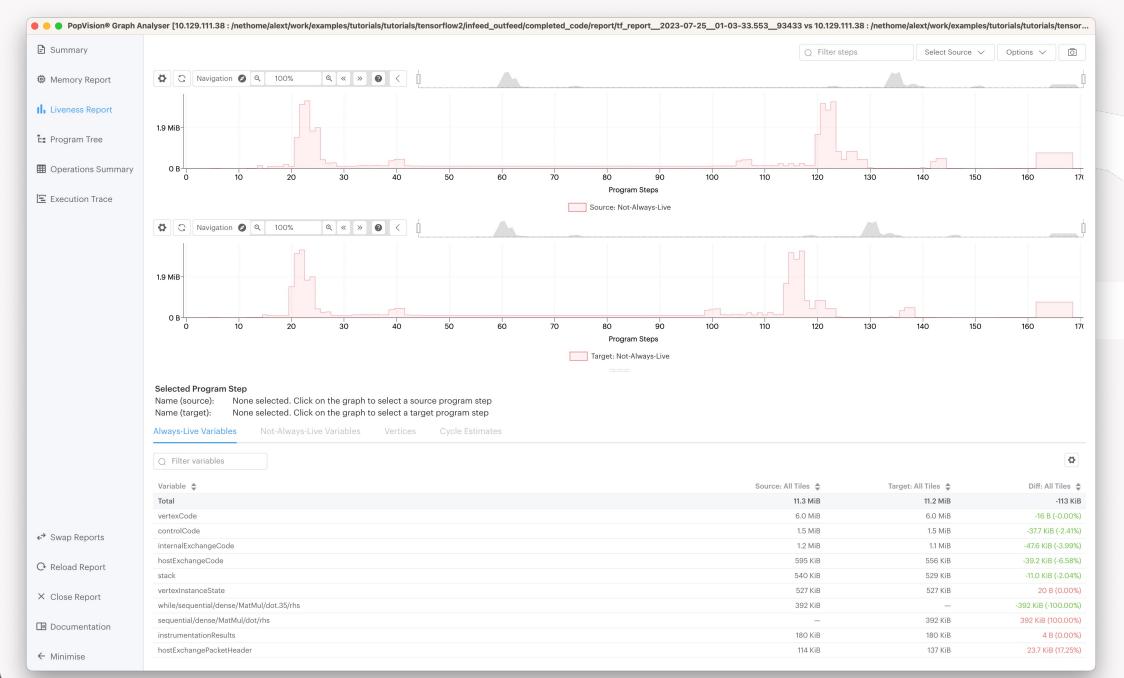
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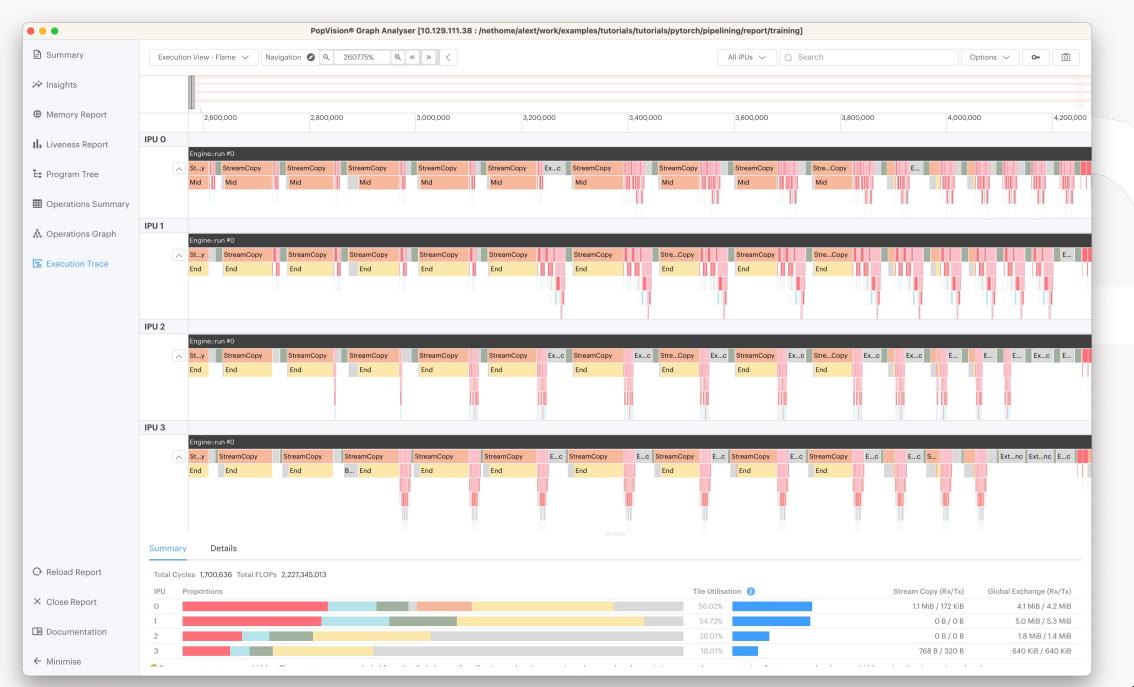
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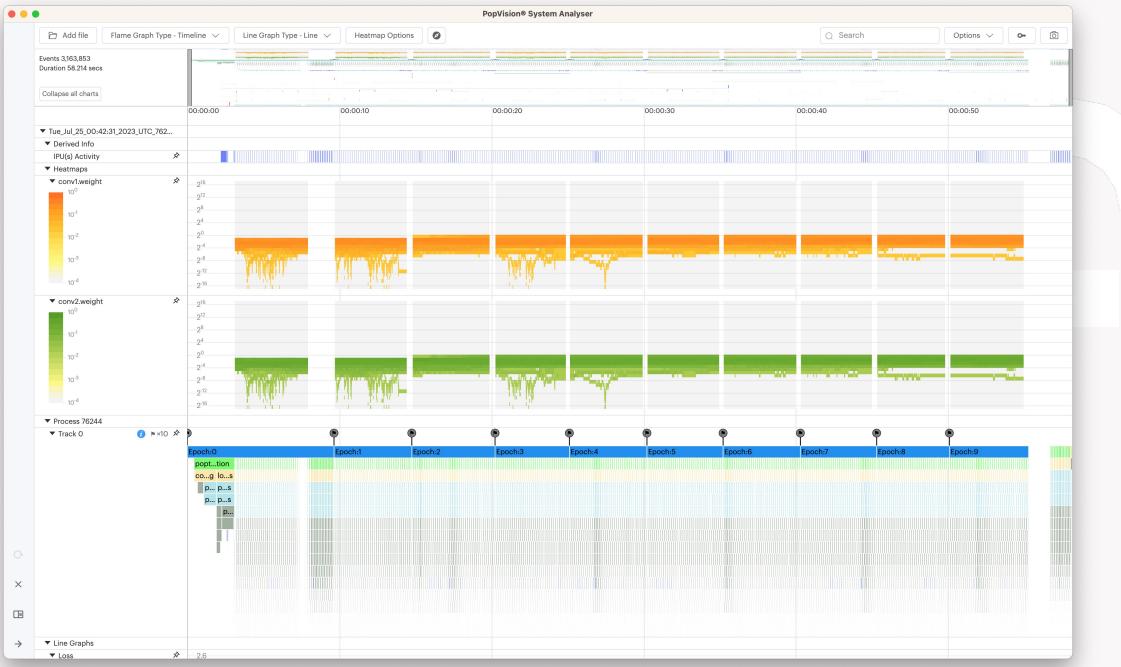


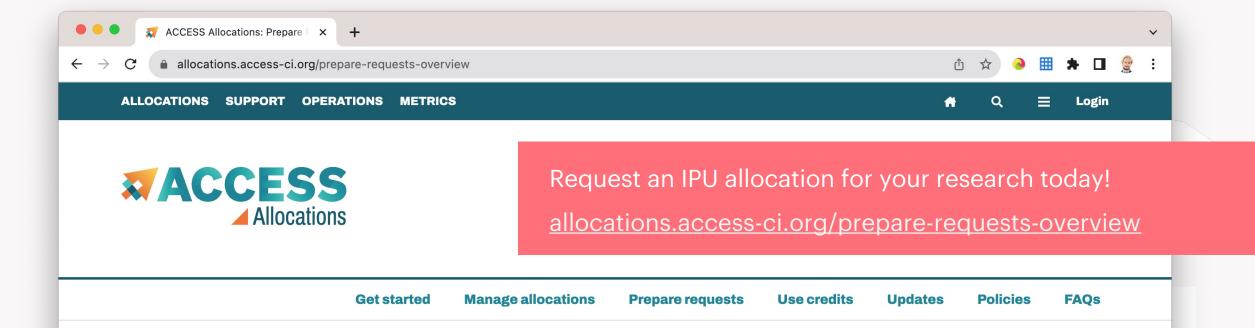


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✓ Aggregate Self time ◆ 3.421 sec 565.996 m 366.950 m	e 38.0% 15 6.3% 15 4.1% 15 3.9%		8.996 secs         100.0           3.615 secs         40.2           1.945 secs         21.6           1.578 secs         17.5	% <b></b>	<ul> <li>poplar::core::IPUTarget::ru</li> <li>poplar::core::IPUTarge</li> <li>poplar::core::IPUTarge</li> <li>poplar::core::Sync</li> <li>poplar::core::</li> </ul>	t::processHspSync :GroupFlow::prepareAccess					
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### Prepare requests: overview

We've organized your options for requesting access to advanced research computing resources into a set of opportunities designed to support needs ranging from new or entry-level exploration to the largest-scale computational experiments. We welcome you to find the opportunity that aligns with your best estimate of your resource needs. And don't worry about starting too small. As you clarify your needs, you can upgrade to a larger-scale opportunity when you're ready.

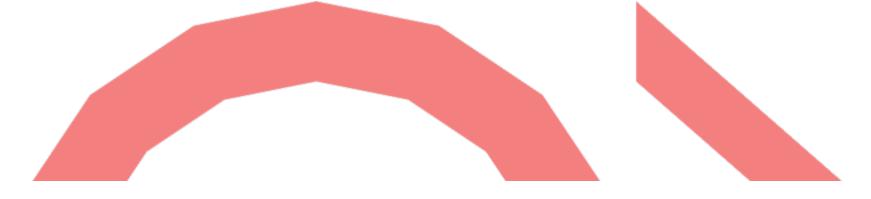
There are four opportunities, which are described below and **<u>compared side-by-side in this table</u>**:

Explore ACCESS



Discover ACCESS

Prepare requests: overview Explore ACCESS Discover ACCESS Accelerate ACCESS Maximize ACCESS Comparison Table



# THANK YOU

Alexander Tsyplikhin alext@graphcore.ai

Request an IPU allocation for your research today! allocations.access-ci.org/prepare-requests-overview

